Display	Name & Description	Range	Display condition	Default value
[redacted]	Output power lower limit	0 % to o/p power high limit; -100 % to o/p power upper limit (in heatcool mode)	PID control	0 (-100 for heat - cool mode)
[redacted]	Output power upper limit	O/p power low limit to 100 %	PID control	100
[redacted]	ON-OFF control hysteresis	0.1 to 99.9	ON-OFF control*	1.0
[redacted]	Hysteresis bias	TC/RTD: -9.9 to 9.9 ° Analog input: -9.9 to 9.9 as per decimal point selected.	[redacted]	[redacted]
[redacted]	Timer	0.0 to 99.9 minutes	[redacted]	[redacted]
[redacted]	[redacted]	[redacted]	[redacted]	[redacted]
dAC	Derivative approach control	0.5 to 5.0 (x band)	PID control	1.0

*NOTE : For operating in ON-OFF mode make Proportional band = 0

Display	Name & Description	Range	Display condition	Default value
CYC.t	Cycle time	USEr/ USP.F/A 15.0	PID control	USEr
[redacted]	Cycle time-user	0.1 to 100.0 sec	Cycle time = USEr	15.0
Any	Anti-reset windup	AUtO/ MANL	PID control	AUtO
[redacted]	Anti-reset windup %	20.0 to 200.0%	ARW = MAnL	100.0
[redacted]	Manual Reset	- 99.9 to 99.9 (for 0.1° resolution) 99 to 999°C (for 1°) -999 to 999 (for analog input)	Proportional band > 0 and Integral time = 0.	0

If Set Mode = All and Zone PID = YES, The parameters except the shaded ones (i.e. Pb-1, It-1, dt-1) will be prompted.

If Set Mode = Zone and Zone PID = YES, the following parameters will be prompted.

Display	Name & Description	Range	Display condition	Default value
[redacted]	Zone number	1 to 4	Zone PID= YES(in level4)	1
2.SP.n	Zone set point	SPLL to SPHL	____	0
Pb-n*	Proportional band	0 to 400.0°	____	10
[redacted]*	Integral time	0 to 3600 sec.	Pb - n > 0	120
[redacted]*	Derivative time	0 to 200 sec.	Pb - n > 0	30

***NOTE:** For Proportional band, Integral time and Derivative time n = 1 to 4

PARAMETER EXPLANATIONS :

- **AUTO TUNING:**

Auto tuning is a function whereby the controller learns the process characteristics by itself and automatically sets the required P,I and D values. The new P,I,D parameters will be stored in non-volatile memory automatically. TUNE ON is indicated by 'T' LED blinking. (For detailed explanations of PID parameters refer USER GUIDE).

- **OUTPUT POWER LIMITS:**

These parameters are used to limit the minimum and maximum controller output power. The output power lower limit will ensure that a minimum percentage of output (as per requirement) is available in case any process disturbances or setpoint changes occur. The output power high limit ensures that in case any process disturbance or set point changes occur, the maximum value of output is limited to a value as per requirement.

- **TIMER:**

TIMER is main output restart time. In this main output once turned OFF will turn ON only after set time even if the temperature has increased and is more than the set temperature. This is needed to prevent the compressor from restarting in a short time (less than the set time).

- **CYCLE TIME:**

There are 3 selectable modes for programming cycle time:
USEr: User can program the cycle time. The mode will be altered to AutO when put to autotune.
Usr.F: User can fix the cycle time. This has the highest priority.
AutO: This is recommended. The cycle time value is calculated automatically during autotune.

- **ANTIRESET WINDUP:**

The anti-reset windup (ARW) inhibits the integral action until the PV is within the proportional band thus reducing overshoot on start-up. If the selection is -
1. AutO: The value will be calculated automatically during autotune (Recommended).
2. ManL: The value can be fed manually by the user.

5. LEVEL 2 - AUXILIARY OUTPUT MODES

Display	Name & Description	Range	Display condition	Default value
[redacted]	Set 2 Mode *	ALMA/NONE /Fd/REU	Not for Heat-cool mode.	ALMA
[redacted]	Set 2 Type	Abs / dEU	Set2 mode = Fd / rEV.	dEU
[redacted]	Set 2 Value	SPLL to SPHL	Not prompted if Set2 mode = alarm & alarm mode = S. Brk.	0
[redacted]	Proportional band-Cool	0.0 to 4000	Heat-cool mode	0.0
[redacted]	Cycle time-Cool	0.1 to 1000 Sec.	Pb-C>0	15.0

NOTE: * - If set2 mode = none, no other parameters will be prompted.

Display	Name & Description	Range	Display condition	Default value
[redacted]	Hysteresis	0.1 to 999°C	1. Set2 mode=Fd/rEV/ ALrM (not sensor break); 2. Heat cool mode (Pb-C=0)	1.0
[redacted]	Hysteresis bias	TC/RTD: -99 to 99°C Analog input: -99 to 999 as per decimal point selected.	1. Set2 mode=Fd/rEV /ALrM (not sensor break); 2. Heat-cool mode (Pb-C=0)	0.0
[redacted]	Alarm1 mode	OFF / dUHI /dULO/bAnd /FSHI /FSLO /SbPt	Set2 mode=ALrM	dUHI
[redacted]	Alarm latch	OFF / On	These parameters are not prompted if Alarm1 mode is OFF.	OFF
[redacted]	Hold Alarm	OFF / On		OFF
[redacted]	Relay status for Alarm1	En / dEn		En
[redacted]	Alarm Annunciator	OFF / On		OFF
[redacted]	Analog low scaling	-999 to 9999	For Analog retransmission if Main output = Relay2 in Level 4	0
[redacted]	Analog high scaling	-999 to 9999	For Analog output if Main output = Relay2	1000

Display	Name & Description	Range	Display condition	Default value
[redacted]	Sensor error level Incase of sensor failure the output can be set to high or low value of range.	HIGH/LOW	For Analog output if Main output = Relay2	HI GH

NOTE:
In **HC mode** only the following parameter will be prompted :-

1. Set 2 value - this parameter will be prompted as db (dead band)
2. Proportional band - cool (Pb-C)
3. Cycle time - cool (cyc.t)

In case of analog retransmission only the following parameters will be prompted:

1. A-LO : Analog low scaling.
2. A-HI : Analog high scaling.
3. S.ERR : Sensor error level.

Display is with fixed 1^{o} resolution for TC/RTD and as per decimal point selected for analog input.

PARAMETER EXPLANATIONS :

- **SET 2 MODE:**

AlrM: Set2 can be programmed as alarm.
NonE: If set2 is not required it can be programmed as none.
Fd: Set2 programmed in cooling mode.(output ON when above the setpoint).
rE: Set2 programmed in heating mode.(output ON when below the setpoint)

- **SET 2 TYPE:**

AbS: Absolute alarm is a self-existent alarm independent of the main set point.
DEV: The alarm is activated at an error on the main set point.

- **ALARM MODES:**

(Refer **USER GUIDE** for detailed explanation).

- **ALARM LATCH:**

When Latch is ON, the alarm once activated remains activated even when the error is removed. To deactivate the alarm, it has to be acknowledged by selecting AL-NO from the front online options and pressing [redacted]

- **HOLD ALARM:**

When HOLD is ON, in any alarm mode, it prevents an alarm signal on power-up. The alarm is enabled only if the process temperature is within the alarm range.

- **ALARM ANNUNCIATOR:**

When alarm annunciator is ON, during alarm condition, visual annunciation is given by the upper display altering between AL-NO and process temperature where NO is the alarm number. The annunciator may be disabled by selecting function ANN as OFF.

- **SENSOR ERROR LEVEL :**

This parameter determines the analog retransmission output level in case of sensor failure. For eg : In case of 4-20mA retransmission output, if the sensor error level is set to High, 20mA will be available at the output at all times incase of input sensor failure.

6. LEVEL 3 - ALARM 2 MODULE (OPTIONAL)

Display	Name & Description	Range	Display condition	Default value
[redacted]	Alarm2 mode	OFF/dUHI /dULO/bAnd /FSHI/FSLO /S.brK.	Alarm 2 should be available.	dUHI
[redacted]	Alarm latch	OFF/On	These parameters are not prompted if Alarm 2 mode is OFF.	OFF
[redacted]	Hold Alarm	OFF/On		OFF
[redacted]	Relay status for Alarm1	En/dEn		En
[redacted]	Alarm Annunciator	OFF/On		OFF
[redacted]	Set 3 Value	SPLL to SPHL	These parameters are not prompted if Alarm 2 mode is OFF/brk.	0
[redacted]	Alarm Hysteresis	0.1 to 99.9 OC for TC/RTD; 1 to 99 OC for analog input.		1.0
[redacted]	Hysteresis bias	-99 to 99°C (for TC/ RTD); -99 to 99 for AIN models decimal point as per selected		0.0

PARAMETER EXPLANATIONS:
For parameter explanations refer Level 2.

7. LEVEL 4 - SPECIAL FUNCTIONS

Display	Name & Description	Range	Display condition	Default value
[redacted]	Heat-cool mode The controller can be operated in heat-cool mode if this selection is YES.	NO/YES	___	NO
[redacted]	Zone PID	NO/YES	___	NO
[redacted]	Main Output	(PLY1 AOUt) PLY2	___	PLY1/ AOUt
[redacted]	SSR Output	NO/YES	SSR output model	NO
[redacted]	Soft start time	OFF, 000 to 999 minutes.	PID control	OFF
[redacted]	Hand output percentage	OFF,O/P power low limit to O/P power high limit.	PID control	OFF
[redacted]	Ramp mode	OFF/HOLd/ON	___	OFF
[redacted]	Ramp rate	0001 to 9999 degree/hour.	Ramp mode =ON/HOLD.	100
[redacted]	Soak time	0 to1440 minutes	Ramp mode =ON/HOLD.	0
[redacted]	Sensor open condition	AUtO/MANL	PID control	AUtO
[redacted]	Sensor fail power level	0 to100%; -100 to 100 % in case of heat-cool mode.	Sensor open condition = MANL.	0
[redacted]	PV bias (Display Offset)	-999 to +999 for TC (RTD) & -999 to +999 for AIN models decimal point as per selected.	___	0.0

Display	Name & Description	Range	Display condition	Default value
[redacted]	Filter time constant	OFF, 1 to 99 seconds	___	1
[redacted]	Output power dampening	OFF, 1 to 99 seconds	Analog output model.	1
[redacted]	Rounding increment	0.1 to 10.0 for TC/RTD Display as per decimal point selected for analog input.	TC / RTD with resolution = 1°C or Analog input.	1.0
[redacted]	Standby mode	NO / YES	___	NO
[redacted]	Reset all	NO / YES	___	NO

PARAMETER EXPLANATIONS :

- **MAIN OUTPUT:**

The main control output is selectable between Relay1 / Analog output (available across terminals 4 and 5) and Relay2 (available across terminals 2 and 3). If main output is selected as Relay 2, all the control parameters will be applicable to the output connected to Relay 2 but the set point applicable will be Set 1 (main set point). For analog retransmission, the main output must be set to Relay 2 and the analog output (across 4 and 5) will be used for retransmission.

- **SOFT START TIME:**

Soft start time can be programmed in situations where full output is not required at power ON. The time duration for the output to rise from 0% to 100% is programmed as soft start time.

- **HAND OUTPUT PERCENTAGE:**

This parameter can be used when a fixed percentage of output is desired. For example: If 4-20mA analog output is being used and the desired output is 12mA, the hand percentage can be programmed as 50%. This will ensure that the analog output available is fixed 12 mA i.e. 50%. In case of relay output models, the relay ON time and OFF time will be according to the programmed Hand output percentage i.e. For 50% hand o/p percentage and cycle time 15sec, relay will be ON for 7.5sec and OFF for 7.5 sec.

- **RAMP - SOAK:**

The set point ramp feature can reduce thermal shock to the process, reduce temperature overshoot on start-up or set point changes, or ramp the process at a controlled rate. The soak feature can be used to hold the process at a preset temperature for a preset time.

Ramp modes:

Ramp OFF: Controller will be simple PID / ON-OFF controller with P, I, D settings / hysteresis setting by user or default.

Ramp HOLD: Suspends the ramp at the last value.

Ramp ON: Initiates the ramp. Ramp rate and soak time settings as programmed by the user or default.

• **SENSOR OPEN CONDITION:**
The sensor open condition is selectable between Auto and Manual. If the sensor open condition is set to Auto, then all the relays remain off at over range or TC reverse condition. If the selection is Manual then the **sensor fail power level** can be programmed as per requirement.

• **PV BIAS:** (DISPLAY OFFSET)
This function is used to adjust the PV value in cases where it is necessary for PV value to agree with another recorder or indicator, or when the sensor cannot be mounted in correct location.

• **FILTER TIME CONSTANT:**
The filter is an adaptive digital filter that discriminates between measurement noise and actual process changes. If the input signal is increasing too greatly due to measurement noise, increase the filter value. If accurate control is desired, increase the filter time constant whereas if the fastest controller response is required, decrease the filter time constant.

• **ROUNDING INCREMENT:**
This feature can be used to round off the display to a higher value than "1" in cases where the process input and in turn the display is fluctuating. Rounding selections other than 1 cause the process value to round to the nearest rounding increment selected. For example, a rounding increment value of 5 causes 122 to round to 120 and 123 to round to 125. This parameter is not applicable when the resolution is 0.1(for TC/RTD). Set point values, Set point limits, Alarm values, Input Scaling values, and Analog Scaling values are not affected by rounding. The rounding increment is for controller's display only and does not affect (improve or degrade) the control accuracy of the unit.

• **STANDBY MODE:**
This feature is useful during machine wiring. If standby mode is selected as YES, the following conditions exist:

a. All displays are OFF.
b. All outputs are OFF i.e. R1, R2, R3 LEDs are OFF.
c. M LED is ON.
d. Analog output is limited to the lower range.
e. All front keys are disabled.
f. Access to configuration enabled.

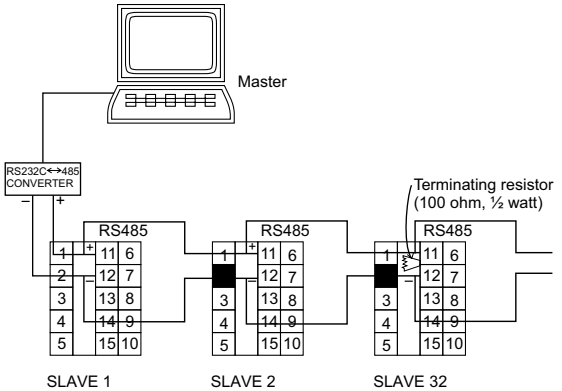
The STND status is preserved on Power OFF.

• **OUTPUT POWER DAMPENING:**
This parameter entered as a time constant in seconds, dampens (filters) the calculated output power. Increasing the value increases the dampening effect. Dampening times longer than, say, one-twentieth to one-fiftieth of the controller's integral time may cause controller instability. This parameter is valid only for analog output models.

8. LEVEL 5 - COMMUNICATION PARAMETERS (OPTIONAL)

Display	Name & Description	Range	Display condition	Default value
[redacted]	Baud Rate	300/600/1200 2400/4800 9600	----	9600
[redacted]	Communication station No.	1 to 99	----	1
[redacted]	Parity	NONE/EVEN Odd/MARK SPCE	----	NONE
[redacted]	Stop bit	1/2	----	1

CONNECTION DIAGRAM



Note:
1. Maximum 32 slave controllers can be connected to the master.
2. The total cable length should not exceed 500 meters.
3. Use shielded twisted -pair cables for RS485 connections.
4. Use terminators having a resistance of 100ohm (½ watt).

8. LEVEL 6 - PROGRAMMABLE PARAMETER LOCKOUT MODULE

Display	Name & Description	Range	Display condition	Default value
[redacted]	User ID	0000 to 9999	___	0000
[redacted]	Program access settings #	ONL/LEVL	___	LEVL

 # If LOCK selection is ONL, the following parameters will be prompted.

Display	Name & Description	Range	Display condition	Default value
[redacted]	Lock Set 1	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock Set 2	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock Set 3	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock tune parameter	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock Hand parameter	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock proportional band	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock integral time	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock derivative time	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock Manual reset parameter	UNLE/REAd /LOCE	___	UNLE
[redacted]	Lock proportional band-cool	UNLE/REAd /LOCE	___	UNLE

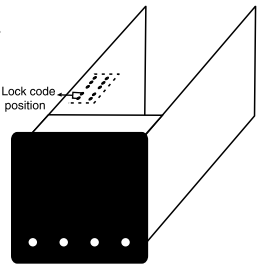
 # If LOCK selection is LEVL, the following parameters will be prompted.

Display	Name & Description	Range	Display condition	Default value
[redacted]	Lock Level 0	UNLK/READ /LOCK	____	UNLK
[redacted]	Lock Level 1	UNLK/READ /LOCK	____	UNLK
[redacted]	Lock Level 2	UNLK/READ /LOCK	____	UNLK
[redacted]	Lock Level 3	UNLK/READ /LOCK	____	UNLK
[redacted]	Lock Level 4	UNLK/READ /LOCK	____	UNLK

[redacted]	Change password	Id-N/Id-Y	____	Id-N
[redacted]	New password	____	NEW = Id-Y	0

NOTE:
UNLK - Full access to the particular level / parameter.
READ - Particular level / parameter can be read but not edited.
LOCK - No access to the particular level / parameter.

Insert jumper to reset the lock - id.



ONLINE DISPLAY OPTION

This function allows user to view online display options.

NOTE:

The parameters shown below are not prompted if they are locked in level 6.

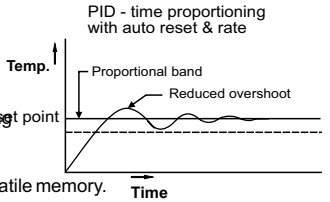
DISPLAY	DESCRIPTION	DISPLAY CONDITION
[redacted]	**Set point 1**	——
[redacted]	**Set point 2**	Online access for Set 2 not valid if Auxillary output = Sensor Break / OFF / Retransmission
[redacted]	**Set point 3**	Online access for Set 3 not valid if Alarm mode = Sensor Break / OFF.
[redacted]	**Auto tune**	Online access for Auto tune is not valid if PB-Heat=0 and HC =no or PB-Cool=0.
[redacted]	**Hand output percentage**	This parameter is not prompted if Pb- H = 0
[redacted]	**Proportional band - heat**	——
[redacted]	**Integral time**	Integral time is not prompted if PB = 0
[redacted]	**Derivative time**	Derivative time is not prompted if PB = 0
[redacted]	**Manual reset**	Manual reset is prompted only if Integral-main=0 and PB-heat > 0.
[redacted]	**Proportional band - cool**	This parameter is prompted only if HC = yes.
[redacted]	**Ramp set point**	This parameter is prompted only if Ramp is ON / Hold. This parameter is read only and cannot be altered.

DISPLAY	DESCRIPTION	DISPLAY CONDITION
[redacted]	**Output percentage**	This parameter is read only and cannot be altered.
[redacted]	**Elapsed soak time**	Note: This parameter is prompted only if Ramp is ON / Hold. This parameter is read only and cannot be altered.
[redacted] / [redacted]	**Temperature unit**	Note: This parameter is not prompted for 0-10 V / 4-20mA. This parameter is read only and cannot be altered.
[redacted]	**Alarm acknowledge 1**	Note: This parameter is prompted only if Alarm1 is ON and Latch is ON.
[redacted]	**Alarm acknowledge 2**	Note: This parameter is prompted only if Alarm2 is ON and Latch is ON.
[redacted]	**Blank**	——

USER GUIDE

- **AUTO TUNING:**

Auto tuning is a function whereby the controller learns the process characteristics by itself and automatically sets the required P,I and D values. The auto-tuning function can be activated at any time during the process after power ON , while temperature is rising or when control has stabilized. Autotune is indicated by T LED blinking. After the auto tuning procedures are completed, the T LED will stop flashing and the unit will revert to PID control by using its new PID values. The PID values obtained are stored in the nonvolatile memory.



The auto-tuning is applied in cases of:

- Initial setup for a new process
- The set point is changed substanitally from the previous auto-tuning value.
- The control result in unsatisfactory.

The following controller parameters are automatically adjusted by Auto- tune according to the characteristics of the process:

Proportional Band (Pb-1)
Integral Time (It-1)
Derivative Time (dt-1)
Input Filter (FtC)

If the control performance by using auto-tuning is still unsatisfactory, the following rules can be applied for further adjustment of PID values:

ADJUST MENT SEQUENCE	SYMPTOM	SOLUTION
(1) Proportional Band (PB)	Slow Response	Decrease PB
	High overshoot or Oscillations	Increase PB
(2) Integral Time (IT)	Slow Response	Decrease IT
	Instability or Oscillations	Increase IT
(3) Derivative Time (TD)	Slow Response or Oscillations	Decrease TD
	High Overshoot	Increase TD

- **PROPORTIONAL BAND:**

Proportional band is the area around the set point where the controller is actually controlling the process; the output is at some level other than 100% or 0%.

Proportional band is expressed in terms of degree centigrade.

If the proportional band is too narrow an oscillation around the setpoint will result. If the proportional band is too wide the control will respond in a sluggish manner, could take a long time to settle at set point and may not respond adequately to upsets.

- **MANUAL RESET:**

Virtually no process requires precisely 50% output on single output controls or 0% output on two output controls. The adjustment called manual reset allows the user to redefine the output requirement at the setpoint. A proportioning control without manual or automatic reset will settle out somewhere within the proportioning band but likely not on the setpoint.

- **INTEGRAL TIME:**

Integral time is defined as the time, in seconds, which corrects for any offset (between setpoint and process variable) automatically over time by shifting the proportioning band. Integral action (also known as “automatic reset”) changes the output power to bring the process to setpoint. Integral times that are too fast (small times) do not allow the process to respond to the new output value. This causes over-compensation and leads to an unstable process with excessive overshoot. Integral times that are too slow (large times) cause a slow response to steady state errors. Integral action may be disabled by setting the time to zero. If time is set to zero, the previous integral output power value is maintained. If integral action is disabled, manual reset is available by modifying the output power offset (“MNL.r” initially set to zero) to eliminate steady state errors. The controller has the feature to prevent integral action when operating outside the proportional band. This feature is called **“antireset wind-up”**.

- **DERIVATIVE TIME**

Derivative action is used to shorten the process response time and helps to stabilize the process by providing an output based on the rate of change of the process. In effect, derivative action anticipates where the process is headed and changes the output before it actually “arrives”. The derivative time is calculated in seconds. Increasing the derivative time helps to stabilize the response, but too much derivative time coupled with noisy signal processes, may cause the output to fluctuate too greatly, yielding poor control. None or too little derivative action usually results in decreased stability with higher overshoots. No derivative action usually requires a wider proportional and slower integral times to maintain the same degree of stability as with derivative action. Derivative action is disabled by setting the time to zero.

- **DERIVATIVE APPROACH CONTROL:**

Derivative approach control (DAC) helps in reducing overshoot at startup. The control output cutoff point is derived as DAC x Proportional band. Note that the DAC value is automatically calculated and fed after autotuning (if tuning is initiated at startup).

- **AUTO-TUNE OF HEAT/COOL SYSTEMS:**

During Autotune of heat/cool systems, the controller switches the cooling output (O2) ON and OFF in addition to the heat output (O1). The heat/cool overlap deadband parameter (db in Level 2) determines the amount of overlap or deadband between the two outputs during Autotune.
For most applications, set this parameter to 0.0 prior to starting Autotune. After the completion of Autotune, this parameter may need to be reset. It is important that external load disturbances be minimized, and if present, other zone controllers idled as these may have an effect on the PID constant determination.
Some water cooled processes exhibit an extreme non-linear gain characteristic. That is, the process cooling gain starts very high and flattens out deeper into the cooling region. This effect may result in regular oscillations at setpoint as the controller applies heat to counteract the effect. These processes may benefit from a lower cooling fan setting and/or reduced water flow in the jacket or manifold. The process heat and cool gains should be balanced as much as possible, and the controller gains adjusted to the process.

- **ANALOG OUTPUT-RETRANSMISSION:**

1. The analog retransmission output feature allows the retransmission of the control output to an external device.
2. The output is scaled by use of Analog low and high scaling points in level 2 of the programming menu. The analog output will be proportional to PV (derived from Analog Low and High scaling.)
3. A-LO : Displays the value that corresponds to 0V, 0/4mA as selected.
   A-HI : Displays the value that corresponds to 10V or 20mA as selected.
4. Note that the main output selection in level 4 has to be relay 2.

- **ALARM MODES:**

1. Absolute alarms (Independent Alarm) :
Absolute alarm is a self-existent alarm independent of the main set point.For eg. If the main set point is 100°C and absolute alarm is set as 110°C, the alarm will be activated at 110°C.
There are two absolute alarms-
Full scale High Alarm: sets off alarm signal when temperature rises above set point to a pre-set temperature above scale minimum. **Refer Fig: d.**
Full scale Low Alarm: sets off alarm signal when temperature falls below setpoint to a pre-set temperature above scale minimum. **Refer Fig: e.**

2. Deviation alarms (Error alarm):
This alarm is activated at an error on the main set point. For eg. If the main set point is 100°C and deviation alarm is set to +5 °C then the alarm will be activated at 100+5=105 °C. Incase of deviation band alarm the alarm will be activated on both sides of set point i.e. At 95 and 105.
There are three deviation alarms -
Deviation High Alarm: sets off alarm signal when temperature rises above a pre-set temperature above the set point. **Refer Fig: a.**
Deviation Low Alarm: sets off alarm signal when temperature falls below a pre-set temperature below the set point. **Refer Fig: b.**
Deviation Band Alarm: sets off alarm signal when temperature rises above or falls below a pre-set temperature above or below the set point. **Refer Fig: c.**

3. BREAK ALARM:
Break Alarm: sets off alarm signal when sensor break / under range occurs.

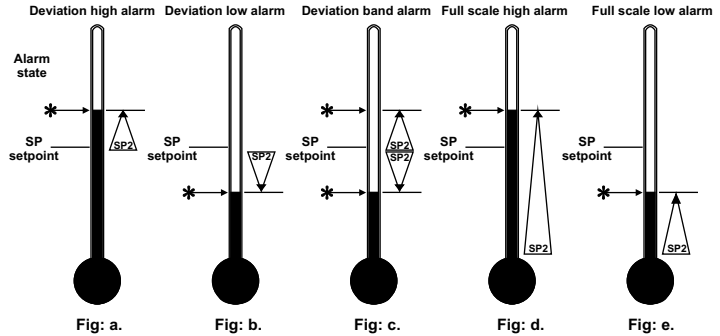


Fig: a. Fig: b. Fig: c. Fig: d. Fig: e.

• **Zone PID:**

There are 4 control Zones each having a set point and associated P, I and D values which can be programmed as per the process requirements. A control Zone is selected automatically and implemented as per the set value programmed, to accommodate changing process requirements. The corresponding P, I,D values will be used to control the process. The main advantage of Zone PID is in processes where there is a requirement of frequent tuning, due to change in setpoint. Consider a case where the process needs to be controlled at two different set points: 100°C and 400°C.

The Zone set points may be programmed as:

1. Zone setpoint 1 (Level1) : 150°C (This implies that for 0 < set1 < 150, Zone1 PID values will be considered.)
2. Zone setpoint 2 (Level1) : 450°C (This implies that for 150 < set1 < 450, Zone2 PID values will be considered.)

The P, I, D values for the respective Zones can be manually fed or can be tuned automatically.

How to tune the Zones

NOTE : Zone setpoint is not the tuning setpoint.

To tune, say, Zone 1 program the following:

1. Set1 (Online) = 100°C (for eg.) (Zone 1 : 0 - 150°C)

   Note: • Set1 < Zone setpoint 1.
   • The PID settings derived after tuning are stored in Zone 1.
   • After tuning, for 0 < Set1 < 150°C, PID settings of Zone 1 are applicable.

2. Program Tune = ON (in Level 1 or Online)

3. After tuning the controller is automatically loaded with the new PID values.

Now to tune the next Zone, Zone 2, program the following:

1. Set 1 (Online) = 400°C (Zone 2 :150 - 450°C)

   Note: • Zone Setpoint 1 < Set 1 < Zone setpoint 2.
   • The PID settings derived after tuning are stored in Zone 2.
   • After tuning, for 150 < Set1 < 450°C, PID settings of Zone 2 are applicable.

Similarly, the four different Zones can be programmed.

Configuration Record Sheet

Enter the value or selection for each prompt on this sheet so you will have a record of how your controller was configured.

Levels	Function Prompt	Value or Selection	Factory Setting
Input Parametrs	[redacted]	_____	J
	PESL	_____	1
	tEmP	_____	°C
	dSCL	_____	0
	ISCL	_____	As per input type selected.
	dSCH	_____	9999
	ISCH	_____	As per input type selected.
	PSCL	_____	no
	[redacted]	_____	750
	[redacted]	_____	-200
Output Parametrs	SEt	_____	ALL
	[redacted]	_____	OFF
	tUNE	_____	P.AU
	[redacted]	_____	PE
	P-LO	_____	0
	P-H1	_____	100
	[redacted]	_____	10
	HYSt	_____	1.0
	HYS.b	_____	0.0
	tmP	_____	0.0
	It-1	_____	120
	[redacted]	_____	30

Levels	Function Prompt	Value or Selection	Factory Setting
Output Parametrs	dAC	_____	1.0
	CYC.t	_____	USEr
	CYC.U	_____	15.0
	Any	_____	AUt0
	Any.P	_____	100.0
	AnL.P	_____	0
Zone Settings	2-no	_____	1
	[redacted]	_____	0
	[redacted]	_____	10
	1t-1	_____	120
	dt-1	_____	30
	[redacted]	_____	0
	[redacted]	_____	10
	1t-2	_____	120
	dt-2	_____	30
	[redacted]	_____	0
	[redacted]	_____	10
	1t-3	_____	120
	dt-3	_____	30
	[redacted]	_____	0
	[redacted]	_____	10
	1t-4	_____	120
	dt-4	_____	30

Levels	Function Prompt	Value or Selection	Factory Setting
Auxiliary Output Modes	[redacted]	_____	ALM2
	[redacted]	_____	dEV
	SEt2	_____	0
	Pb-C	_____	0.0
	CYC.t	_____	15.0
	HYSt	_____	1.0
	HYS.b	_____	0.0
	[redacted]	_____	dUAL
	LtCH	_____	OFF
	HOLd	_____	OFF
	ALM2	_____	En
	AMM	_____	OFF
	A-LO	_____	0
	A-HI	_____	1000
	S.ERR	_____	HIGH
Alarm 2 Module	[redacted]	_____	dUAL
	LtCH	_____	OFF
	HOLd	_____	OFF
	ALM2	_____	En
	AMM	_____	OFF
	SEt3	_____	0
	HYSt	_____	1.0
	HYS.b	_____	0.0

Levels	Function Prompt	Value or Selection	Factory Setting
Special Function	[redacted]	_____	no
	[redacted]	_____	no
	[redacted]	_____	PLY1/AOUt
	SSP	_____	OFF
	[redacted]	_____	OFF
	HAnd	_____	OFF
	MAnP	_____	OFF
	rAtE	_____	100
	SOAt	_____	0
	OPEn	_____	AUtO
	FAIL	_____	0
	[redacted]	_____	0.0
	[redacted]	_____	1
	rndG	_____	1.0
	[redacted]	_____	no
	[redacted]	_____	no
Communication	[redacted]	_____	9600
	[redacted]	_____	1
	[redacted]	_____	nonE
	[redacted]	_____	1

Model No: PID500-110-330

Claimed Accuracy: ± 0.25% of full scale ±1 digit (After 20min warmup time)

Standard used for calibration of the product is traceable to NABL

The calibration of this unit has been verified at the following values:

SENSOR	CALIBRATION TEMP (°C) (0.1 resolution)	DISPLAY VALUE (°C)	SENSOR	CALIBRATION VALUE (0.1 resolution)	DISPLAY VALUE
K	35.0	35.0	Voltage (VDC)	0.0	0.0
	700.0	700.0		10.0	10.0
	1350	1350			
PT100	0.0	0.0	Current (mA)	0.0	0.0
	500.0	500.0		20.0	20.0
	800.0	800.0			

The thermocouple / RTD curves are linearised in this microprocessor based product, and hence the values interpolated between the readings shown above are also equally accurate, at every point in the curve.

Unit is accepted as accuracy is withing the specified limit of claimed accuracy and certificate is valid upto one year from the date of issue.

Disclaimer : "This product is strictly for industrial use and for sale in non European countries only"